# PP004 Parallel Port-Based DSPTÔ 6001 / 6002 CAMAC CONTROLLER REFERENCE MANUAL Revised 03/18/07

Computer Methods 4424 Technology Drive Fremont, CA 94538 510 824 0252 www.computer-methods.com

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## Introduction



Figure 1: PP004 Interface and Cables

The PP004 interfaces an IBM®-compatible PC with a DSPT<sup>™</sup> 6001 / 6002 CAMAC Controller via the PC Parallel Port. This product is designed to replace the functionality of the PC-004 CAMAC interface, which required a 16-bit ISA slot. As newer and faster computers become available, it is increasing difficult to find PCI-based motherboards that support an ISA slot.

The PP004 communicates with the PC through a standard parallel (printer) port operating in EPP mode. Most PCI-based motherboards support EPP mode (enabled via the BIOS). Thus, it is now feasible to upgrade older ISA-based PCs to newer and higher-performance models and continue to utilize existing CAMAC devices. The non-invasive aspect of this interface makes it ideal for use with laptops in the field.

### Hardware Setup

The PP004 is shipped with the following items:

- > PP004 Interface
- IEEE1284 Extension Cable 1.8M (DB25 to DB25)
- ➢ USB A-B Cable 2M
- > CD with Drivers and Diagnostics

Before using the PP004, you must decide how to supply power. The PP004 accepts 5 to 15 volts @ 150ma maximum current. There are two options for power:

- 1. Via USB Connector
- 2. Via 2.1mm Power Connector



Figure 2: Location of Power Select Jumper JU1

Figure 2 illustrates the location of the blue jumper JU1. When shorting pins 1 & 2, the USB connector is selected for power input. When shorting pins 2 & 3, the power jack is selected for input. The power jack can be used with any DC source between 5 and 15 volts such as a 9v 500ma power-adapter (Digikey Part Number T405-ND).

The green LED on the PP004 front panel indicates that power is connected to the board. The LED will flash orange when a DATASTROBE signal is issued (pin 14 of the parallel port connector). The orange indicator is a useful debugging tool for verifying that communication is established between the PC parallel port and the PP004.



Figure 3: Ribbon cable connectors for two controllers

The PP004 is capable of interfacing with two 6001 / 6002 CAMAC controllers. Figure 3 illustrates the location of connectors PL1 and PL2. A controller connected (via the 40-pin ribbon cable) at PL1 will be addressed as Crate 1. Similarly, a controller connected at PL2 will be addressed as Crate 2. Controllers are selected using software commands written to the parallel port's EPP Address register (see **PP004 Parallel Port Commands**).

The PP004 interfaces with the PC bus via the parallel (printer) port using the DB25 extension cable. The parallel port must be configured in **EPP** mode. This is usually one of the available options for printer settings in the BIOS. Other modes (AT, PS2, SPP, ECP) are not supported. EPP mode is considered to be very reliable and offers ample bandwidth for CAMAC data transfer rates.

### PP004 Parallel Port Commands

| Register                          | I/O Port Offset |
|-----------------------------------|-----------------|
| SPP Mode Data                     | 0               |
| SPP Mode Status                   | 1               |
| SPP Mode Control                  | 2               |
| EPP Address                       | 3               |
| EPP Data                          | 4               |
| <b>T</b> 1 1 1 <b>D</b> 1 0 1 1 1 |                 |

The I/O registers for a PC parallel port operating in EPP mode are as follows:

Table 1: Port Offsets for EPP Mode Registers

Communication with the PP004 is handled through EPP Address and Data operations. Many parallel ports require that the SPP Control register be configured with a 0x4 hex to enable EPP transfers. This corresponds to setting control bits **C0**, **C1** and **C3** (active low signals). This is recommended as a one-time initialization step before reading or writing to EPP registers.

Data is written to the crate controller by setting the internal address of the desired CAMAC register using an EPP Address Write (bits D3-D0), followed by an EPP Data Write. Similarly, data is read from the crate by first setting the desired internal address with an EPP Address Write followed by an EPP Data Read. The high order bits (D7-D5) of an EPP Address Write select the desired controller. Table 2 summarizes PP004 commands.

| PP004 Operation  | EPP<br>Register | R/W   |
|--|-----------------|-------|
| Point To CAMAC Crate Controller and Internal Address.<br>Bits <b>D3-D0</b> select address. | Address         | Write |
| Bits <b>D7-D5</b> select crate (0=Crate1, 1=Crate2).<br>( <b>D4</b> is unused)             |                 |       |
| Read Crate LAM Signals   | Address         | Read  |
| Write Data at CAMAC Internal Address*  | Data            | Write |
| Read Data at CAMAC Internal Address*   | Data            | Read  |
| *EPP Data transfer auto-increments pointer to next CAMAC Internal Add                      | ress.           |       |
| Table 2: PP004 Commands  |                 |       |

EPP Data operations increment the pointer to the next CAMAC Internal Address. This reduces the overhead of reading or writing data to successive CAMAC registers. The following table presents a sequence of PP004 operations used to read the module ID (**F3 A0** command) from a CAMAC device assuming the following conditions:

- 1. PP004 Connected to LPT1 (I/O Port Base Address **0x378**)
- 2. CAMAC 6001 / 6002 Controller ribbon cable connected to PL1
- 3. CAMAC Module is located at Station 1

| Desired Operation                        | I/O Port Address | Data       | R/W   |
|--|------------------|------------|-------|
| Initialize SPP Control Register for EPP  | 0x37A            | 0x4        | Write |
| Transfers                                |                  |            |       |
| Set pointer to Internal CAMAC A Register | 0x37B            | 0x3        | Write |
| Write <b>0</b> to <b>A</b> Register      | 0x37C            | 0x0        | Write |
| Write <b>3</b> to <b>F</b> Register      | 0x37C            | 0x3        | Write |
| Write 1 to N Register                    | 0x37C            | 0x1        | Write |
| Set pointer to CAMAC Cycle Register      | 0x37B            | 0x7        | Write |
| Initiate CAMAC Cycle                     | 0x37C            | 0x0        | Write |
| Read QX and Encoded LAM Register         | 0x37C            | QX and LAM | Read  |
| Read CAMAC data high byte                | 0x37C            | RH         | Read  |
| Read CAMAC data middle byte              | 0x37C            | RM         | Read  |
| Read CAMAC data low byte                 | 0x37C            | RL         | Read  |

All values in hexidecimal unless otherwise noted

Table 3: Sample CAMAC Command F3 A0 (Read Module ID)

#### PP004 Diagnostic Program "EPPDIAG.EXE"

The 32-bit application **EPPDIAG** provides low-level access to parallel port I/O registers. A setup file for installing **EPPDIAG** can be found on the **PP004 Applications CD** distributed with the product. In addition, the VC++ project used to build **EPPDIAG** is also distributed on the application CD. **EPPDIAG** can be used to check a system for EPP compatibility and verify proper operation of the PP004. Figure 4 illustrates the front panel of this diagnostic program.

The **Initialize Control Register** button performs the operation of writing 0x4 to the SPP Control register. This is highly recommended before attempting any EPP operations. The **Test for EPP Mode** button performs a series of operations that detect the presence of EPP Mode support. If this test is not successful than the port is not operating in EPP mode. Check the BIOS or driver settings for the parallel port. Most PCI-based systems support all of the parallel port modes. Some systems support only SPP and ECP modes. ECP is not the same as EPP and is not supported by the PP004.

Assuming that EPP mode operation is possible, the operator first selects a port register to be accessed. Figure 5 illustrates the registers that are available in EPP mode (SPP Data and SPP Status are generally not used for EPP transfers).

If doing a write operation, the hexadecimal value is typed into the value box and the **Write** button is clicked. If doing a read operation, the **Read** button is clicked and the result is returned in the Value box. The **Loop** buttons continuously repeat an operation until the **Stop** button is clicked. Looping is generally used as a debugging tool with an oscilloscope to trace signals on the PP004 board.

| 💑 EPP Diagnostic   | X  |
|--|--|
| Port Address Ox378 Add Value                               | Initialize Control Register<br>for EPP Transfers |
| Port Register  | Test for EPP Mode                                |
| Value<br>0x  | Operation<br>Read Loop<br>Write Loop             |
| CAMAC Operation<br>Station: 1 -<br>F[3] A[0]<br>Device ID: | Help<br>E xit                                    |

Figure 4: Front Panel of EPP Mode Diagnostic

| P  | Port Register    |          |
|----|------------------|----------|
| 8  | SPP/PS2 Data 🛛 💌 |          |
|    | SPP/PS2 Data     | <u> </u> |
| 19 | SPP Status       | _        |
| 8  | SPP Control      |          |
| E  | EPP Address      |          |
| E  | EPP Data         |          |
| LE | EPP Data         | 100      |

Figure 5: Port Register Selection

This diagnostic could be used to enter the **F3 A0** CAMAC Command sequence described table 3 and retrieve the module ID. This is a very good method of verifying the proper connections and operation of the PP004. The step-by-step instructions for executing this sequence are as follows:

| Desired Operation                                | Port Register | Value       | Button |
|--|---------------|-------------|--------|
| Initialize SPP Control Register for EPP          | SPP Control   | 0x4         | Write  |
| Transfers  |               |             |        |
| Set pointer to Internal CAMAC A Register         | EPP Address   | 0x3         | Write  |
| Write <b>0</b> to <b>A</b> Register              | EPP Data      | 0x0         | Write  |
| Write <b>3</b> to <b>F</b> Register              | EPP Data      | 0x3         | Write  |
| Write <b>1</b> to <b>N</b> Register              | EPP Data      | 0x1         | Write  |
| Set pointer to CAMAC Cycle Register              | EPP Address   | 0x7         | Write  |
| Initiate CAMAC Cycle                             | EPP Data      | 0x0         | Write  |
| Read QX and Encoded LAM Register                 | EPP Data      | QX and LAM  | Read   |
| Read Module ID                                   | EPP Data      | Hi Byte     | Read   |
| Read Module ID                                   | EPP Data      | Middle Byte | Read   |
| Read Module ID                                   | EPP Data      | Low Byte    | Read   |
| All values in hexadecimal unless otherwise noted |               |             |        |

Table 4: F3 A0 (Read Module ID) Command Sequence Using EPPDIAG Application

The **CAMAC Operation** command group conveniently performs the sequence described in table 4. After selecting the desired CAMAC station, clicking the **F[3] A[0]** button will set up the command, issue a CAMAC cycle and read back a 16 bit value (formed by reading and combining

the CAMAC RM and RL bytes). The result is displayed (in decimal) as the **Device ID**. The front panel LED will flash orange to indicate a data transfer.

#### Accessing the I/O Port in Win98, WinNT, Win2000 and WinXP

In DOS and Windows 98, applications are allowed to execute "\_outp" and "\_inp" instructions that directly access the PC's I/O port. However, on WinNT, Win2000 and WinXP platforms, these instructions are considered "privileged" and must run under ring 0 in protected mode.

The Winlo library allows 32-bit Windows applications to directly access I/O ports and physical memory. It bypasses Windows protection mechanisms by using a combination of a kernel-mode device driver and several low-level programming techniques.

The WinIO DLL and driver set is included with the EPPDIAG project on the PP004 Applications CD.

#### PSP9100 Driver Set Compatibility

Drivers to support PSP9100 are located on the application CD in the folder **PSP9100\_PP004**. The common elements of PSP9100 drivers are encapsulated in the file **CAM6001.ASM**. By setting the appropriate compiler directives, this component generates an object module (OBJ) that supports a variety of language platforms. The file **CAM6001.ASM** has been modified to support the PP004 interface. Descriptions of the key files provided on the application CD are:

| FILENAME     | DESCRIPTION   |
|--------------|---|
| CAM6001.ASM  | Assembly language driver exposing a set of functions    |
|              | to read and write to the 6001 / 6002 Controller         |
| CAMTURBO.OBJ | Object module compiled for Turbo Pascal 4               |
| CAMTUNIT.OBJ | Object module compiled for Turbo Pascal Unit            |
|              | encapsulating CAM6001 functions                         |
| CAMBASIC.OBJ | Object module compiled for Basic                        |
| CAMACPRO.OBJ | Object module compiled for Professional Fortran         |
| CAMACMS.OBJ  | Object module compiled for Microsoft Pascal and C       |
| CAMAC_C.OBJ  | Object module compiled for C without Pascal attribute   |
| CAMTUNIT.TPU | Turbo Pascal Unit encapsulating CAM6001 functions       |
| MAKE9100.BAT | Batch file that compiles object modules for the various |
|              | language platforms                                      |
| NAFTEST.PAS  | Turbo Pascal program source for sending and             |
|              | receiving CAMAC commands to/from 6001 / 6002            |
|              | controller  |
| NAFTEST.EXE  | NAFTEST executable compiled for PP004                   |
|              | Table 5: PSP9100 Driver Files                           |

It should be noted that the PP004 does not support DMA transfers analogous to the PC004. Instead, the **DMAI** and **DMAO** functions in CAM6001.ASM are modified to issue repeated calls to **CAMI** and **CAMO** respectively. Data rates in the vicinity of 225K bytes per second have been achieved with the PP004 implementation of this driver.

When specifying a transfer length of three bytes in the **DMASET** function, the PP004 reads/writes the three CAMAC data bytes to a **DWORD** location. This implies that data is read (or stored) in the PC on **DWORD** (32 bit) boundaries. This adheres to the same convention implemented by the Jorway SCSI controller drivers. To move 24- bit wide CAMAC data on boundaries other than 32-bit, simply modify the addressing in the **DMAI** and **DMAO** functions in the CAM6001.ASM driver as needed and recompile the object module using the appropriate compiler directive applicable to the platform in use.

The object modules supplied on the application CD were compiled using Microsoft MASM Version 6.0 and Linker 5.13. The NAFTEST utility was compiled using Borland Turbo Pascal 5.0. Development was performed on a Win98 platform using a DOS Shell.

#### PPCAM32.DLL AND CAMTEST

The **PPCAM32** folder contains a Visual C++ 5.0 DLL project for PPCAM32.DLL. This DLL contains a set of C functions that communicate with a CAMAC crate controller via the PP004 connected to the parallel port. The **CAMTEST** folder contains a simple dialog-based MFC application that uses the DLL to send simple commands and retrieve data to/from a CAMAC crate. These projects are provided as samples of tested code to communicate successfully with a CAMAC crate over a range of Windows platforms.

The following table documents the functions exported in PPCAM32.DLL. The DLL and corresponding header and library files are available in the "CAMTEST" project folder.

| PPCAM32.DLL Function Declarations                          |  |  |
|--|--|--|
| Function   | Description                              |  |
| <pre>void Crate_set(int *p_C);</pre>                       | Selects a CAMAC Crate.                   |  |
| p_C = pointer to Crate Number                              | Subsequent calls to <b>cami</b> and      |  |
|  | camo are directed to this crate.         |  |
| Void cami (int *p_N, int *p_F, int *p_A, int               | Reads a 16-bit value from the            |  |
| <pre>*p_DRW,int *p_Q,int *p_X);</pre>                      | CAMAC crate. The state of the            |  |
| p_N = pointer to station                                   | "O" and "X" flags are returned           |  |
| p_F = pointer to function                                  | a and X hage are retained.               |  |
| p_A = pointer to address                                   |  |  |
| p_DRW = pointer to data                                    |  |  |
| p_Q = pointer to Q flag                                    |  |  |
| p_Q = pointer to X flag                                    |  |  |
| Void camo (int *p_N, int *p_F, int *p_A, int               | Writes a 16-bit value to the             |  |
| *p_DRW,int *p_Q,int *p_X);                                 | CAMAC crate. The state of the            |  |
| p_N = pointer to station                                   | "Q" and "X" flags are returned.          |  |
| p_F = pointer to function                                  | Ũ  |  |
| p_A = pointer to address                                   |  |  |
| p_DRW = pointer to data                                    |  |  |
| $p_Q = pointer to Q flag$                                  |  |  |
| $p_Q = pointer to X mag$                                   |  |  |
| cam124(Int *p_N, Int *p_F, Int *p_A, unsigned long         | 24-bit version of <b>cami</b> . Reads a  |  |
| (see cami)   | 24-bit value from the CAMAC              |  |
|  | crate.                                   |  |
| <pre>camo24(int *p_N,int *p_F,int *p_A,unsigned long</pre> | 24-bit version of <b>camo</b> . Writes a |  |
| *p_DRW, int *p_Q, int *p_X);                               | 24-bit value to the CAMAC crate.         |  |
| (see camo)   |  |  |
| unsigned int cami();                                       | Returns the LAM of the highest           |  |
|  | priority station (or 0 for no LAM).      |  |
| <pre>camcl(unsigned int *ZCI_bits);</pre>                  | Writes the CAMAC control                 |  |
| ZCI = pointer to ZCI bit configuration                     | register with the desired bit            |  |
| Bit I - Z CYCLE  | configuration                            |  |
| BIT $2 - C$ CYCLE  |  |  |
| BIL 3 - SEI I, CAMAC INHIBII                               |  |  |
| BIL 4 - SEI BUS INHIBII REG                                |  |  |
| DIC 5 - RESEI BUS INNIBII REG                              |  |  |
| Bit $7 = \text{RESET} 6002  ACL & BUS INHIBIT REG$         |  |  |
| dmaset(int *p C int *NOB int *OBL unsigned int             | Initializes the DLL for a "dma"          |  |
| *NTR);   | transfor The DD004 emulates              |  |
| p C = pointer to Crate Number                              | DMA transfer by parforming               |  |
| NOB = pointer to Number of Bytes per transfer              | Divia transfer by performing             |  |
|  | repeated calls to cami (or camo)         |  |

| QBL = (not used)  | that are optimized for speed.   |
|---|---|
| NTR = Number of transfers   |   |
| <pre>int dmai(int *p_N,int *p_F,int *p_A,unsigned char *p_DRW,int *p_E); p_N = pointer to station p_F = pointer to function p_A = pointer to address p_DRW = pointer to data p_E = (not used)</pre>                         | Performs a "dma" transfer from<br>the device to the data buffer<br>based on the parameters passed<br>in <b>dmaset</b> . |
| <pre>int dmao(int *p_N,int *p_F,int *p_A,unsigned char<br/>*p_DRW,int *p_E);<br/>p_N = pointer to station<br/>p_F = pointer to function<br/>p_A = pointer to address<br/>p_DRW = pointer to data<br/>p_E = (not used)</pre> | Performs a "dma" transfer from<br>the data buffer to the device<br>based on the parameters passed<br>in <b>dmaset</b> . |
| <pre>unsigned int camcyc(unsigned int *NTR);<br/>NTR = (not used)</pre>   | Returns the number of transfers<br>completed in the last <b>dmai</b> or<br><b>dmao</b> call.                            |

Table 6: Descriptions of Functions Exported in PPCAM32.DLL

Figure 6 illustrates the dialog presented by the CAMTEST application. The operation of this dialog is self-explanatory and should be familiar to users with CAMAC experience. The dialog allows the operator to select a crate, station, function and address. Clicking the **EXECUTE** button will issue a **CAMI** or **CAMO** call (depending on the function selected). Radio buttons reflect the status of the **Q** and **X** flags. DMAI calls can be tested by entering the number of transfers, selecting the byte transfer length and clicking the **READ** button. The results of the transfer are logged in the list box.

| 💑 CAMAC Function   | n Test Panel                             |  | × |
|--|--|--|---|
| Instruction Cycle<br>Crate<br>1<br>statioN<br>1<br>Address<br>0<br>Function<br>3 | Value<br>Execute<br>Q Q Flag<br>Q X Flag | DMAI<br># Transfers<br># of Bytes<br>1<br>Read |   |
|  | ОК                                       |  |   |

Figure 6: CAMTEST Application Dialog

## PPCAM32.INI (PPCAM32.DLL CONFIGURATION)

PPCAM32.DLL assumes that CAMAC crates 1 & 2 will be cabled to connectors PL1 and PL2 (respectively) of a PP004 interfaced to the "primary" parallel port at I/O address 0x378. Similarly, crates 3 & 4 are assumed to be connected to a PP004 at the "secondary" parallel port at I/O address 0x278.

The primary and secondary parallel port assignments can be altered by editing the

file **PPCAM32.INI** and modifying the port address specifications. This file will be located in the same folder as PPCAM32.DLL.

Suppose the parallel port of the target system does not support EPP mode. If a second (EPP-compatible parallel port) is installed, it will be assigned an I/O port address by the Windows Plug and Play driver (assume this new address is 0x278). To configure the DLL for this I/O address, the primary port for the PP004 must be set to 0x278 in the **PPCAM32.INI** file. Changes to the INI file configuration will take effect the next time the DLL is loaded.

On fast motherboards, there may be timing issues when initiating a CAMAC cycle. The DLL must wait at least 1 usec for a CAMAC cycle to be completed. The INI parameter **Delay Cycles** specifies a delay period (in machine cycles) after a CAMAC cycle is initiated to allow the cycle to complete. This period may be increased as needed on faster machines.

#### ACAP COMPATIBILITY (CMPP004 Kernel Mode Driver)

The PP004 supports operation with **ACAP** – an application for engine combustion analysis. ACAP is a 16-bit Windows® application that communicates with the CAMAC 6001 (or 6002) controller using an ISA-based PC004 interface card. Most contemporary mother boards no longer support the ISA bus making it difficult to migrate the **ACAP** application to newer computers running Windows 2000 or XP.

The **CMPP004\_SETUP.EXE** file (distributed on the PP004 Applications CD) installs a special set of drivers and DLLs that interface the PP004 with the ACAP application. At present, the only version of **ACAP** tested with the PP004 interface is **6.0B**. However, previous versions of ACAP are expected to be compatible with the PP004.

It is required that the ACAP application already be installed on the target system before running the **CMPP004\_SETUP.EXE** setup file. During the setup process, the user will specify the location of the **ACAP** program folder. The setup file will then perform the following actions:

- 1. Copy the existing WINCAMAC.DLL and WINCAM32.DLL files in the ACAP program folder to a subfolder named "DLL"
- 2. Overwrite the WINCAMAC.DLL and WINCAM32.DLL files in the ACAP program folder with versions that support the PP004
- 3. Install the CAMTEST.EXE utility in the ACAP program folder.
- 4. Install the CMPP004.SYS driver in the Windows System folder
- 5. Update the Windows registry with configuration information for the CMPP004.SYS driver
- 6. Prompt the user to reboot

It is assumed that the PP004 is connected to the primary printer port (LPT1) located at port address 0x378. If this is not the case, it will be necessary to modify the registry to point to the correct port address. To determine the port address of the printer port, use the Device Manager as follows:

- 1. Right-click on My Computer and select Properties
- 2. Select the Hardware tab
- 3. Click the *Device Manager* button
- 4. Expand the *Ports* section (see figure 7)
- 5. Right-click on the printer port being used for the PP004 and select *Properties*
- 6. Select the *Resources* tab (see figure 8)



Figure 7: Locating the Printer Port in Device Manager

| Printer Port (LPT1) Prope | erties                     | <u>?×</u>      |
|---------------------------|----------------------------|----------------|
| General Port Settings D   | river Resources            |                |
| Printer Port (LPT         | [1]                        |                |
| Resource type             | Setting                    |                |
| input/Output Range        | 0378 - 037F<br>0778 - 077B |                |
| Setting based on: Curre   | nt configuration           | <u> </u>       |
|                           | se automatic settings      | Change Setting |
| Conflicting device list:  |                            |                |
| No conflicts.             |                            | *              |
|                           |                            | OK Cancel      |

Figure 8: Displaying the Port's Resources

In the example of figure 8, the port address for the LPT1 printer port is 0378 (hex). To edit the appropriate registry key, follow these steps:

- 1. Click Start, Run
- 2. Type the program name "REGEDIT" and click OK
- 3. Navigate to the following key: HKEY\_LOCAL\_MACHINE\SYSTEM\CurrentControlSet\Services\cmpp004\Parameters (see figure 9)

- 4. Right-click on IoPortAddress and select Modify
- 5. Enter the hexadecimal value of the port address obtained from Device Manager and click OK
- 6. Reboot the system.



Figure 9: Editing the IoPortAddress registry key

#### **References**

Parallel Port Complete: Programming, Interfacing & Using the PC's Parallel Printer Port Copyright 2000 Axelson, Jan, Lakeview Research, 5310 Chinook Ln., Madison, WI USA 608 241 5824 mailto:<u>info@lvr.com</u>, URL:<u>http://www.lvr.com</u>.

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